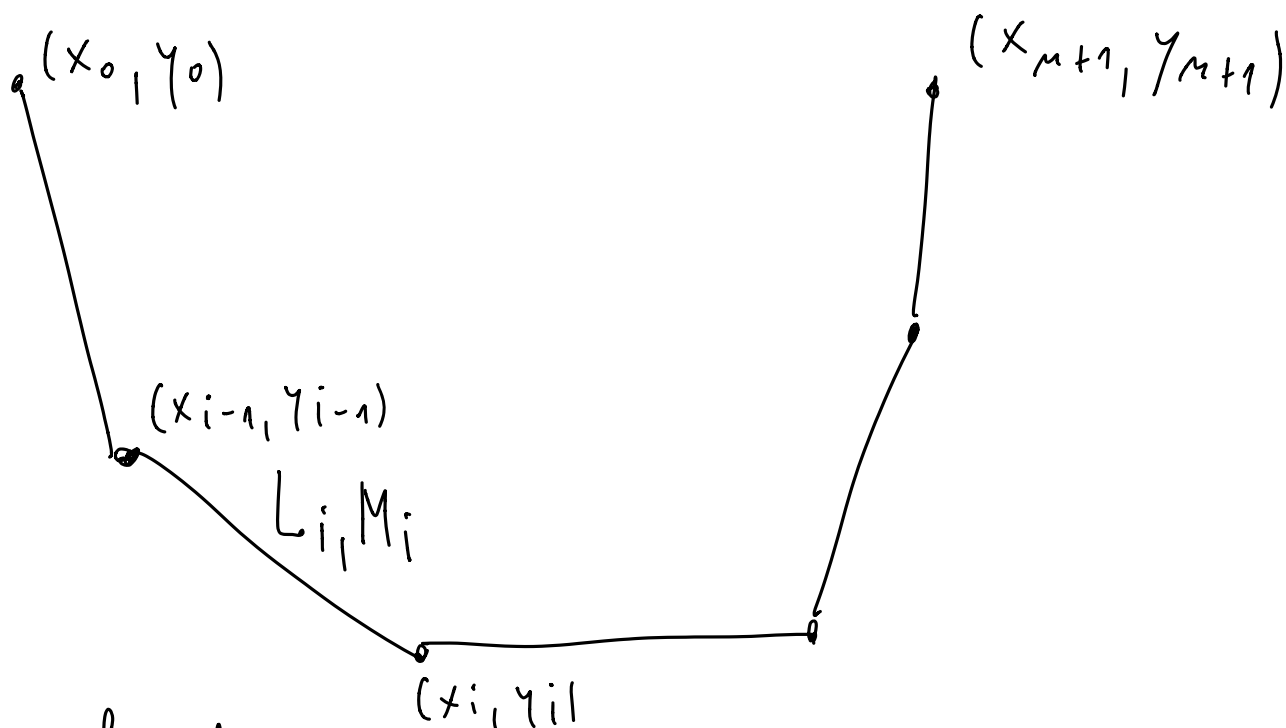


Diskretna verižnica



Diskretna verižnica je sestavljena iz $m+1$ členov (homogenih):

L_i , $i = 1, 2, \dots, m+1$; dolžine

M_i , $i = 1, 2, \dots, m+1$; mase

Verižnico opremo tako, da fiksiramo prvi členek (eno od krajišč) v (x_0, y_0) , zadnjega pa v (x_{m+1}, y_{m+1}) .

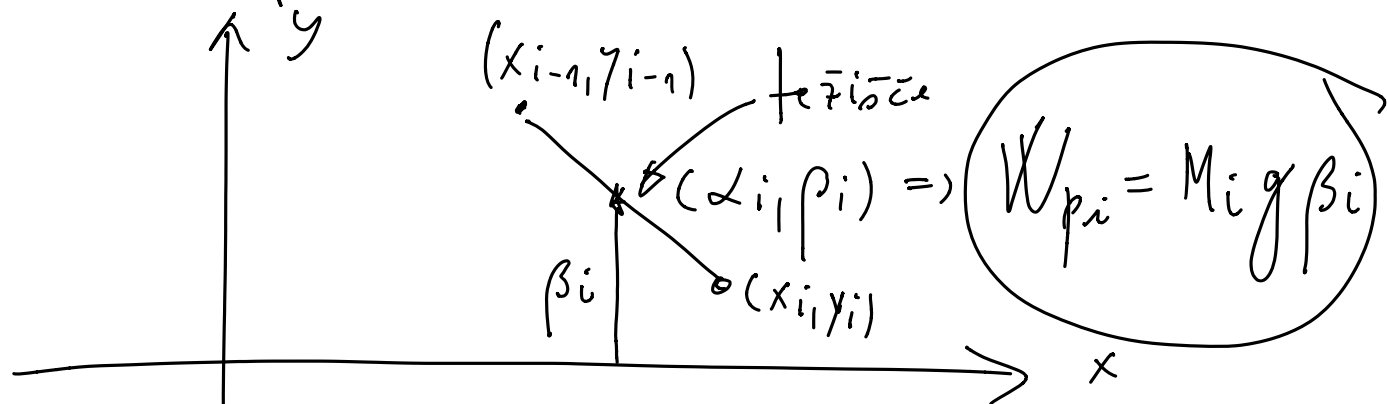
Če krajšča verižnice, ki določajo i -ti členek, označimo z (x_{i-1}, y_{i-1}) ter (x_i, y_i) , potem se malo

masas, č. izračunamo koordinate
 $(x_i, y_i); i = 1, 2, \dots, n$.

Verižnica "želi minimizirati" potencialno
 energijo sistema členkov!

W_p - potencialna energija sistema:

Ema palica:



$$\Rightarrow \beta_i = \frac{y_{i-1} + y_i}{2} \Rightarrow W_{pi} = M_i g \frac{y_{i-1} + y_i}{2}$$

$$\text{Vse palice: } W_p = \sum_{i=1}^{n+1} W_{pi}$$

$$= \sum_{i=1}^{n+1} M_i g \frac{y_{i-1} + y_i}{2}$$

| Sčemo $\min W_p$, kar pomeni iskanje lokacije

ni odvisna od y !

Normirana potencialna energija:

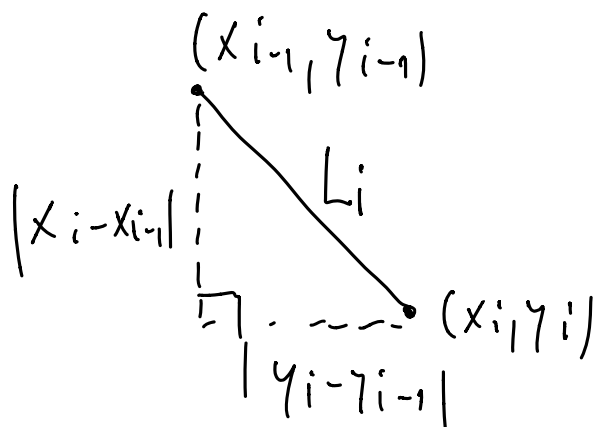
$$\min_{x, y} F(x, y) = \min_{x, y} \sum_{i=1}^{n+1} M_i \frac{y_{i-1} + y_i}{2}$$

$$x = (\overset{\text{znamen}}{\underset{\text{meznaraka}}{x_0}}, \overset{\text{znamen}}{\underset{\text{meznaraka}}{x_1}}, \dots, \overset{\text{znamen}}{\underset{\text{meznaraka}}{x_{n+1}}})^T, y = (\overset{\text{znamen}}{\underset{\text{meznaraka}}{y_0}}, \overset{\text{znamen}}{\underset{\text{meznaraka}}{y_1}}, \dots, \overset{\text{znamen}}{\underset{\text{meznaraka}}{y_{n+1}}})^T$$

→ znamen
— meznaraka

Minimum iščemo pri določenih pogojih:

$$(x_i - x_{i-1})^2 + (y_i - y_{i-1})^2 = L_i^2, i=1, 2, \dots, n+1$$



Iščemo torej vezan ekstrem!

$$G(x, y, \lambda) = F(x, y) + \sum_{i=1}^{n+1} \lambda_i ((x_i - x_{i-1})^2 +$$

$$(y_j - y_{j-1})^2 - L_j^2$$

Isicemo klasični ekstrem (minimum)

funkcije $G(x, y, \lambda)$.

Poiskati moramo stacionarne točke G :

$$\frac{1}{2} \frac{\partial G}{\partial x_i} = 0, \quad i = 1, 2, \dots, n,$$

$$\frac{1}{2} \frac{\partial G}{\partial y_i} = 0, \quad i = 1, 2, \dots, n,$$

$$\frac{\partial G}{\partial \lambda_i} = 0, \quad i = 1, 2, \dots, n.$$

$\Rightarrow$

$$\lambda_i (x_i - x_{i-1}) - \lambda_{i+1} (x_{i+1} - x_i) = 0, \quad i = 1, 2, \dots, n$$

$$\lambda_i (y_i - y_{i-1}) - \lambda_{i+1} (y_{i+1} - y_i) = - \frac{\mu_i + \mu_{i+1}}{4}, \quad i = 1, 2, \dots, n$$

$$(x_i - x_{i-1})^2 + (y_i - y_{i-1})^2 = L_i^2, \quad i = 1, 2, \dots, n+1$$

Dobivamo sistem $3n + 1$ nelinearnih enačb

za $m+1$ meznank: $x_1, x_2, \dots, x_m, y_1, y_2, \dots, y_m,$
 $\lambda_1, \lambda_2, \dots, \lambda_{m+1}$.

Naprej uvedemo t. i. relativne koordinate:

$$\xi_i = x_i - x_{i-1}; \quad i=1, 2, \dots, m+1,$$

$$\eta_i = y_i - y_{i-1}; \quad i=1, 2, \dots, m+1.$$

Sledi:

$$x_i = x_0 + \sum_{j=1}^i \xi_j; \quad i=1, 2, \dots, m+1,$$

$$y_i = y_0 + \sum_{j=1}^i \eta_j; \quad i=1, 2, \dots, m+1.$$

Sistemu se praviše v obliki

$$\lambda_i \xi_i - \lambda_{i+1} \xi_{i+1} = 0, \quad i=1, 2, \dots, m,$$

$$\lambda_i \eta_i - \lambda_{i+1} \eta_{i+1} = -\frac{1}{2} \mu_i, \quad i=1, 2, \dots, m,$$

$$\xi_i^2 + \eta_i^2 = L_i^2; \quad i=1, 2, \dots, m+1,$$

$$\text{tj. } \mu = \frac{M_i + M_{i+1}}{2}.$$

Optimimo, da je $\lambda_i \xi_i$ konstantno
za $\forall i$:

$$\lambda_i \xi_i = -\frac{1}{2\mu} ; i=1, 2, \dots, n+1$$

(red circle around μ) mu zmanjšan

Torej je $\lambda_i = -\frac{1}{2\mu \xi_i}$, od koder

dobimo

$$-\frac{1}{2\mu \xi_i} \eta_i + \frac{1}{2\mu \xi_{i+1}} \eta_{i+1} = -\frac{1}{2} \mu_i, i=1, 2, \dots, n$$

Gledi: $\frac{\eta_{i+1}}{\xi_{i+1}} = \frac{\eta_i}{\xi_i} - \mu_i ; i=1, 2, \dots, n$

Če nadaljeujemo, dobimo

$$\frac{\eta_i}{\xi_i} = \left(\frac{\eta_1}{\xi_1} \right)_{i=1}^{i=n} - \mu_1 - \mu_2 - \dots - \mu_{i-1}$$

$$= v - \mu \sum_{j=1}^n \rho_j \quad ; \quad i=1, 2, \dots, n+1.$$

Upoštevamo

$$\xi_i^2 + \eta_i^2 = L_i^2 / \xi_i^2$$

$$1 + \left(\frac{\eta_i}{\xi_i} \right)^2 = \frac{L_i^2}{\xi_i^2}$$

Od tod dobimo

$$\xi_i = \pm \frac{L_i}{\sqrt{1 + \left(v - \mu \sum_{j=1}^{i-1} \rho_j \right)^2}} \quad ; \quad i=1, 2, \dots, n+1$$

Nadaje izpeljemo

$$\eta_i = \xi_i \left(v - \mu \sum_{j=1}^{i-1} \rho_j \right)$$

Dobili smo, da je $\xi_i = \xi_i(\mu, v)$

$$\eta_i = \eta_i(\mu, v)$$

$$1 + \frac{\mu+1}{\dots}$$

$$U(u, v) = \sum_{i=1}^n \left(f_i - (x_{m+1} - x_0) \right)$$

$$= \cancel{x_1 - x_0} + \cancel{x_2 - x_1} + \cancel{x_3 - x_2} + \dots + \cancel{x_{m+1} - x_m} - \cancel{x_{m+1}} + x_0 = 0 \Rightarrow \boxed{U(u, v) = 0}$$

$$V(u, v) = \sum_{i=1}^n \left(M_i - (y_{m+1} - y_0) \right) \Rightarrow 0 \Rightarrow \boxed{V(u, v) = 0}$$

Kako rešujemo sistem

$$U(u, v) = 0$$

$$V(u, v) = 0 \quad ?$$

- Lahko uporabimo Newtonovo metodo v dveh dimenzijah:

$$H(u, v) = \begin{bmatrix} U(u, v) \\ V(u, v) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

$$(u, v) = X:$$

$$H(X) = \begin{bmatrix} U(X) \\ V(X) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = 0$$

$$\begin{matrix} (r+1) & (r) & I^{-1} & (r) & (r) & (r) \end{matrix}$$

$$X = X - \bigcup_{H(X)} \cdot H(X)_{, v=0,1, \dots}$$

Namesto tega rešujemo sistem:

$$\bigcup_{H(X^{(v)})} \Delta X^{(v)} = -H(X^{(v)})$$

$$\boxed{A \cdot x = b}$$

- Lahko pa uporabite fsolve za reševanje sistema nel. enačb (optimization toolbox).
- Lahko tudi uporabite fmincon na zvečnem problemu!