

Najti delce v magnetnem polju:
Lagrangeov in Hamiltonov pristop

Če od prej vemo, da je potencial lahko odvisen od hitrosti in je rila podana z

$$F_i = -\frac{\partial U(q_i, \dot{q}_i, t)}{\partial q_i} + \frac{d}{dt} \frac{\partial U(q_i, \dot{q}_i, t)}{\partial \dot{q}_i} \quad (*)$$

Ker je rila na najhit delce v magnetnem polju odvisna od hitrosti, moramo imeti tak primer. Pojdimo $U(\vec{r}, \vec{v}, t)$!

Večja Lorentzova rila

$$\vec{F} = e(\vec{E} + \vec{v} \times \vec{B}) \quad (*)$$

Obratujemo se modifikaciji \vec{v} upoštevamo skalarne in vektorske potenciale, (ϕ, \vec{A}) , 4 dim. $\vec{A} = (\phi, \vec{A})$

$$\vec{B} = \nabla \times \vec{A} \quad \text{in} \quad \vec{E} = -\nabla \phi - \frac{\partial \vec{A}}{\partial t}$$

kar zjutraj zadošča Maxwellovim enačbam $\nabla \cdot (\nabla \times \vec{v}) = 0$ za $\forall \vec{v}$

$$\nabla \cdot \vec{B} = 0 \quad \text{in}$$

$$\nabla \times \vec{E} = -\nabla \times \nabla \phi - \nabla \times \frac{\partial \vec{A}}{\partial t} = -\frac{\partial}{\partial t} \nabla \times \vec{A} = -\frac{\partial \vec{B}}{\partial t}$$

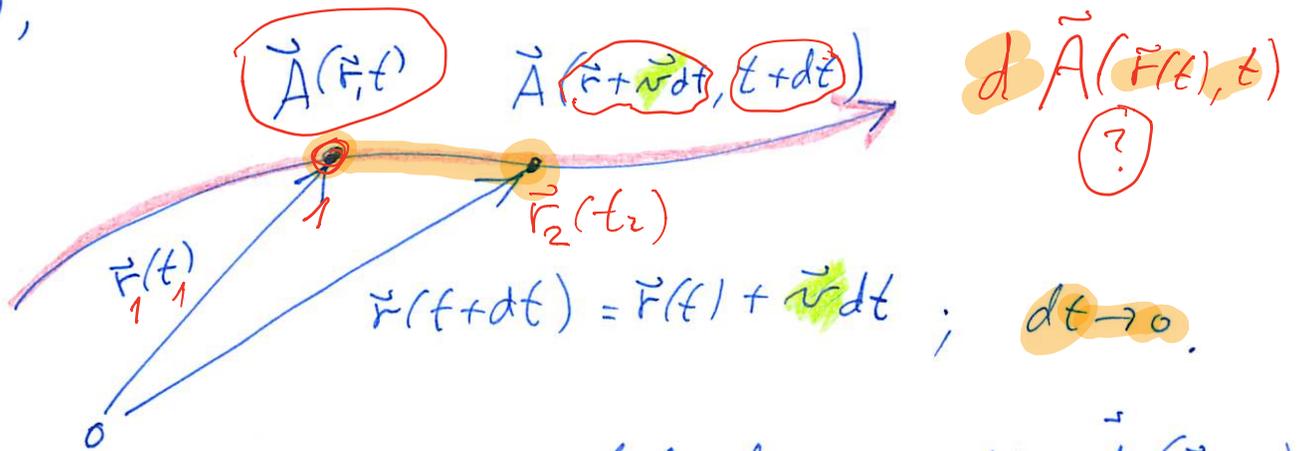
Silo torej lahko izračunamo tako

$$\vec{F} = e \left[-\nabla \phi - \frac{\partial \vec{A}}{\partial t} + \vec{v} \times (\nabla \times \vec{A}) \right], \quad \vec{A}(\vec{r}, t) \quad \phi(\vec{r}, t)$$

kar lahko redko preoblikujemo v obliko (*); (člen $\frac{d}{dt} \frac{\partial U}{\partial \dot{q}_i}$ je človeku odvisno gradienta glede na \vec{r})

$$\frac{d}{dt} \nabla_{\vec{v}} U; \quad \vec{F} = -\frac{\partial U}{\partial \vec{r}} + \frac{d}{dt} \frac{\partial U}{\partial \vec{v}} \quad (*)$$

Spominimo se "skalarne funkcije" odnosa.
 Druge delce, ki se gibajo po trajektoriji $\vec{r}(t)$,



Delce se gibajo v vektorju po $\vec{A}(\vec{r}, t)$
 in v časovnem intervalu dt se na
 mestu delca pojavi sprememba za $d\vec{A}$,

$$dA_x = A_x(\vec{r} + \vec{v} dt, t + dt) - A_x(\vec{r}, t) =$$

$$= \frac{\partial A_x}{\partial x} dx + \frac{\partial A_x}{\partial y} dy + \frac{\partial A_x}{\partial z} dz + \frac{\partial A_x}{\partial t} dt =$$

$$= \left[\left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) A_x + \frac{\partial A_x}{\partial t} \right] dt =$$

gradient skalar

$$= \left(\vec{v} \cdot \nabla A_x + \frac{\partial A_x}{\partial t} \right) dt$$

Enako velja za y in z , torej

$$\frac{d\vec{A}}{dt} = \frac{\partial \vec{A}}{\partial t} + (\vec{v} \cdot \nabla) \vec{A}$$

velja: $\begin{pmatrix} \vec{v} \cdot \nabla A_x \\ \vec{v} \cdot \nabla A_y \\ \vec{v} \cdot \nabla A_z \end{pmatrix} \sim$ "odnos v smeri $\frac{\vec{v}}{v}$ "

Kelgiti tuda: $\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c} = \dots$?

$$\vec{v} \times (\nabla \times \vec{A}) = \nabla(\vec{v} \cdot \vec{A}) - (\vec{v} \cdot \nabla)\vec{A},$$

Ken joo \vec{v} hituost delca. Dolostenu \vec{v} grotus sika po komponenten (oli veijomenu...):
 leva stuan (komponenta x):

$$x: \quad v_y (\nabla \times \vec{A})_z - v_z (\nabla \times \vec{A})_y =$$

$$= v_y \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) - v_z \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right)$$

Denna stuan:

$$\frac{\partial}{\partial x} (v_x A_x + v_y A_y + v_z A_z) - \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) A_x =$$

$$= \left(v_x \frac{\partial A_x}{\partial x} - v_x \frac{\partial A_x}{\partial x} \right) + \left(v_y \frac{\partial A_y}{\partial x} - v_y \frac{\partial A_x}{\partial y} \right) + \left(v_z \frac{\partial A_z}{\partial x} - v_z \frac{\partial A_x}{\partial z} \right)$$

D.N.

res enslo
 $\rightarrow x, \rightarrow y, z$

Unimmo se redaj ma

$$\vec{F} = e \left[-\nabla \phi - \frac{\partial \vec{A}}{\partial t} + \vec{v} \times (\nabla \times \vec{A}) \right]$$

in uporabimo:

$$\frac{d\vec{A}}{dt} = \frac{\partial \vec{A}}{\partial t} + \nabla(\vec{v} \cdot \vec{A}) - \vec{v} \times (\nabla \times \vec{A})$$

$$\nabla(\vec{v} \cdot \vec{A}) = \vec{v} \cdot \nabla \vec{A}$$

obizome

$$\vec{F} = e \left[-\nabla(\phi - \vec{v} \cdot \vec{A}) - \frac{d\vec{A}}{dt} \right] = \frac{d\vec{A}}{dt} = \frac{d}{dt} \vec{v} \cdot \nabla(\vec{v} \cdot \vec{A})$$

$$= e \left[-\nabla(\phi - \vec{v} \cdot \vec{A}) + \frac{d}{dt} (-\nabla(\vec{v} \cdot \vec{A})) \right] =$$

$$= -\nabla U + \frac{d}{dt} \nabla U$$

$$\vec{F} = -\nabla U + \frac{d}{dt} \nabla U$$

e

$$U = e\phi - e\vec{v} \cdot \vec{A}$$

$$= U(\vec{r}, \vec{v}, t). \quad \vec{F} = e\vec{E} + e\vec{v} \times \vec{B}$$

Lagrangova funkcija je torej

$$\vec{B} = \nabla \times \vec{A}$$

$$L = \frac{1}{2} m v^2 - e\phi + e\vec{v} \cdot \vec{A}$$

ustrezne enačbe gibanja so izvede z Lorentzovo silo in pogojem moment je

$$\vec{p} = \frac{\partial L}{\partial \vec{v}}$$

$$\vec{p} = \nabla_{\vec{v}} L = m\vec{v} + e\vec{A}$$

Hamiltonova funkcija je definirana

$$E = H = \vec{p} \cdot \vec{v} - L = \frac{|\vec{p} - e\vec{A}|^2}{2m} + e\phi \quad \Rightarrow \quad \vec{F} = m\vec{a}$$

$$= m v^2 + e\vec{v} \cdot \vec{A} - \frac{1}{2} m v^2 + e\phi - e\vec{v} \cdot \vec{A} = \frac{1}{2} m v^2 + e\phi$$

! kje je \vec{A} ? $\rightarrow \vec{p}$

\leftarrow se mi izračuna z impulsi

$$= \frac{|\vec{p} - e\vec{A}|^2}{2m} + e\phi = H(\vec{r}, \vec{p}, t) \quad \vec{p} = m\vec{v} + e\vec{A}$$

Komentar:

Lorentzova sila je $\perp m\vec{v}$,

$$e\vec{v} \times \vec{B}, \text{ zato je } \vec{p} = \vec{F} \cdot \vec{v} = 0,$$

torej polje ne deluje z močjo (ne opravlja mehanskega dela).

Torej ne spremenj energije in zato ne vpliva na izvede

$$\frac{1}{2} m v^2 + e\phi$$

$$\vec{B} \times; \vec{E} \checkmark$$

Vpliva pa, sicer, na obliko tiru.

\vec{p} ↑
fotoni
↓
→
 $e^{-\beta H}$ L
 $\sim e^{-\beta H}$; $\beta = \frac{1}{k_B T}$
Statistična fizika



! \vec{B} !

$$QM: \quad H = \frac{(\vec{p} - e\vec{A})^2}{2m} + e\phi = \frac{(-i\nabla - e\vec{A})^2}{2m} + V$$

enote: $\hbar = 1$